

**DICOM**  
**Second Generation Radiotherapy**

**Supplement 213**

**Enhanced RT Image  
and  
RT Patient Position Acquisition Instruction**

**DICOM Working Group 07  
Radiotherapy**

# Scope of Supplement

- **Radiotherapy Imaging for Patient Position Detection:**  
Various imaging technologies result in various IODs
- **Advice to Procedure Execution:**  
Acquisition Devices are instructed about details of Acquisition

## ***Scope of Supplement 213: Red parts:***

Technology	Result IODs	Acquisition Instruction IOD
Projection / RT Image	Enhanced RT Image -> Sup 213	Included -> Sup 213
CT	CT	Included -> Sup 213
MR	MR	Future Extension
Ultrasound	US	Future Extension
Surface Scanning	Surface	Future Extension
Transponder Marker	Segmentation, Fiducials	Future Extension
...others	...others	Future Extension

## **2 IODs for RT Image**

- Enhanced RT Image
- Enhanced Continuous RT Image

## **1 Instruction IOD**

- RT Patient Position Acquisition Instruction

## **Several Macros**

- Applicability (to RT Radiation Sets, RT Radiations...)
- Geometry (Image Source and Receptor in respect to Equipment)
- Signal Generation (KV, MV, potentially in future: other modalities)

## **Macro usage across all 3 IODs:**

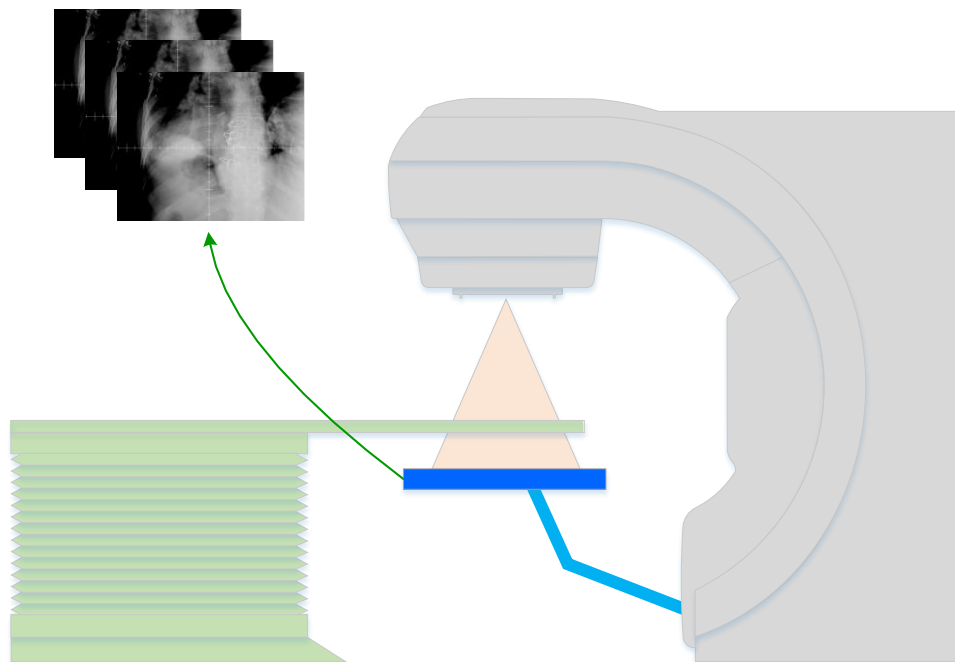
- RT Image IODs: Recording parameters used during acquisition
- Instruction IOD: Specifying parameters to be used during acquisition

(substantially same scope of content as in 1<sup>st</sup> Generation)

## Image Characteristics

- Projection Image
- May be:
  - Single Frame
  - Couple of Frames
  - Continuous acquisition (MPEG) (\*)

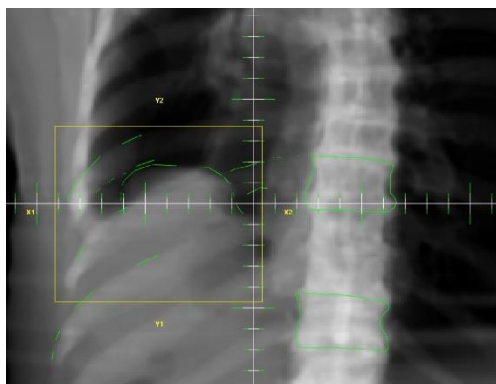
(\*) Supported by annotation of selected Image Frames only (instead of annotation all Frames -> huge, but unnecessary size)



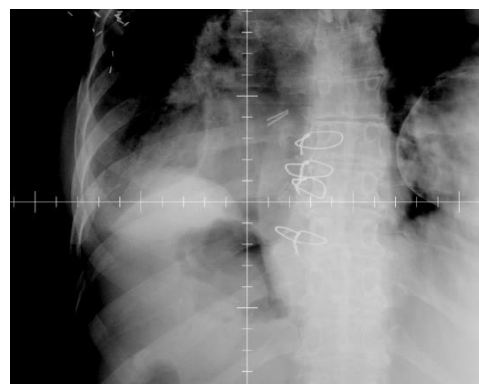
## Image Object may represent

- **Images acquired**  
before / during / after therapeutic Radiation
- **Images re-constructed from 3D Images prior to Treatment**  
'DRRs', 'Reference Images', constructed in Treatment Planning phase
  - Used for verification:  
Comparison against acquired Images

DRR



Acquired



## Patient Position Detection and Correction

- Acquire RT Image with patient on table.
- Relate current Patient Position in respect to treatment device
- Determine correction of Patient Position:
  - Determine current beam geometry in respect to patient
  - Relate current beam geometry to planned beam geometry (in respect to patient)
  - - as needed -  
Align position and orientation of patient to match planned beam geometry

### ⇒ RT Image provides well-defined path of geometric calculation:

- From: treatment beam in device coordinates
- To: Patient FOR
- For various type of treatment devices
- Crucial for correct placement of therapeutic radiation

## Patient Position Monitoring

- RT Images acquired during Therapeutic Radiation Delivery
- Using various acquisition frequencies / trigger points
- Various Modes of Use, namely
  - Pre-Treatment verification  
To verify, that the position is within limits
  - During-treatment observation  
Ensure that position stays within certain limits
  - Post-Treatment Monitoring  
To verify, that the position was within limits  
Assess amount of motion

## **Geometric Content**

- Generalized description of geometric relation of Image
  - to Treatment device
  - to Patient positioning device

## **Therapeutic Beam-related Content**

- State of Device where the Image relates to:
  - Meterset / Time
  - Related to device states (e.g. gantry rotation, collimation etc.)
  - Description of Beam Modifiers in generalized approach of 2<sup>nd</sup> Gen

## **Therapeutic Context**

- RT Radiation, RT Radiation Set, RT Plan
- Treatment Session and Treatment Fraction



## **Use of 2<sup>nd</sup> Gen concepts**

- RT Image Context to RT Radiation Sets, RT Radiations
- Using Equipment Coordinate System
- Generalizing geometry specification to handle variety of Imaging devices and Treatment Device geometries – re-use Macros
- Using 2<sup>nd</sup> generation macros to describe Patient Position, Beam Modifiers, Radiation – re-use Macros

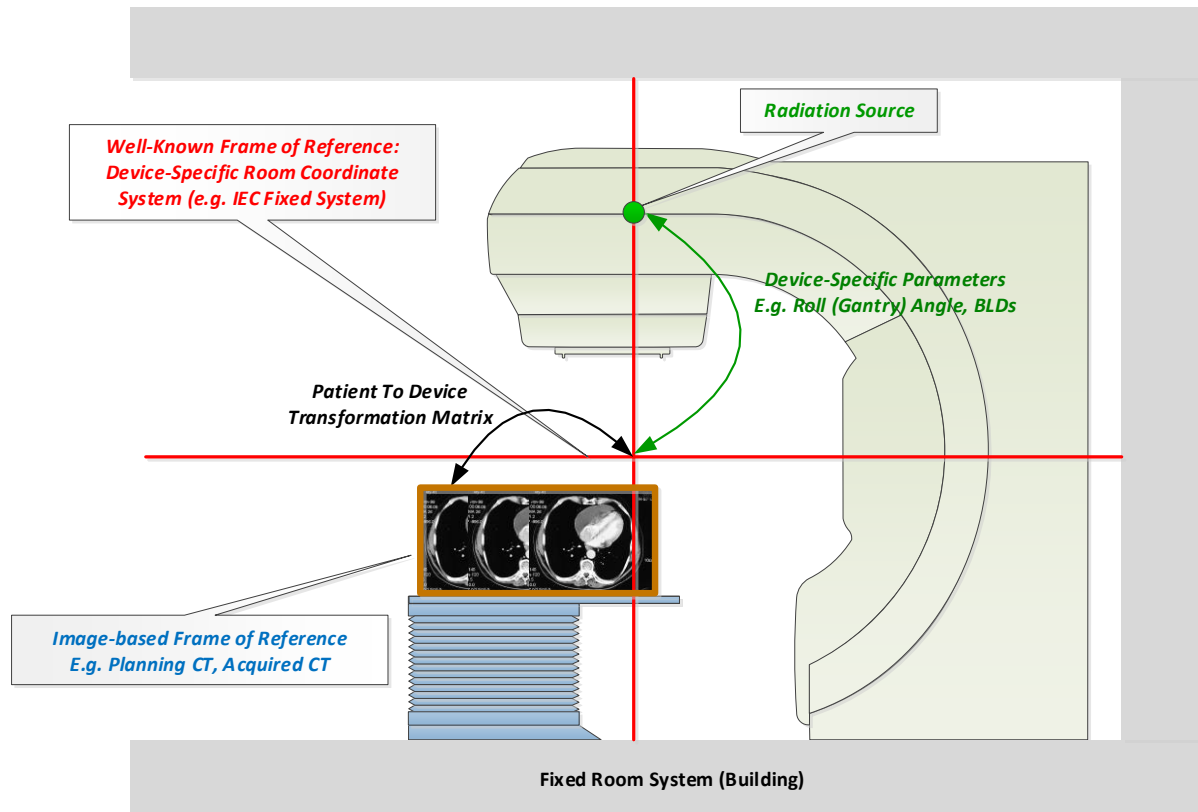
## **Use of Enhanced Multi-Frame Approach**

- Benefit from Multi-Frame Functional Groups formalism
- Stay in line with current Multi-Frame of other IODs

## **Cleaning up / strengthening / expanding...**

- the historically grown patchy structure and representation of 1<sup>st</sup> Gen RT Image IOD

## 2<sup>nd</sup> Gen Use of application of Equipment FOR and Patient FOR



## RT Patient Position Acquisition Instruction IOD

Contains specification for (as applicable):

- **RT Patient Support Device Position**

Specified Position in respect to Equipment Coordinate System at which acquisition shall be performed

- **Acquisition Device Position**

Positions of Acquisition Devices in respect to Equipment Coordinate System when artifacts are acquired

- **Acquisition Execution Parameters**

Parameters to be used when artifacts are acquired

- **Acquisition Triggers**

Specifies when devices should perform the acquisition

### **Current Coverage in Supplement 213:**

MV / KV, Projection and Volumetric Image Acquisition

**Other modalities / technologies may be added to this IOD by future supplements**

IOD designed for extensibility

# RT Pat. Position Instruction

<b>Task</b>	<b>Index / Workitem Code</b>
	<b>Applicability Scope</b> References to Radiation Instances / Treatment Groups
<b>Subtask (1-n)</b>	<b>Index / Specialized Workitem Code</b>
	<b>Acquisition Template Identifier</b>
	<b>Baseline Radiation Reference</b>
	<b>RT Device Distance Reference</b>
	<b>Acquisition Initiation</b>
	<b>Source Signal Generation</b> <ul style="list-style-type: none"><li>- kV Generation</li><li>- MV Generation</li></ul>
	<b>RT Device to Patient Geometry</b> <ul style="list-style-type: none"><li>- Projection Imaging Geometry</li><li>- 3D Imaging Geometry</li></ul>
	<b>Device-Specific Parameters</b>
	<b>Additional Devices / Parameters</b>
	<b>Position Reference Instances</b>

# One Subtask Example

## Task

Workitem Code = (121702, DCM, "RT Patient Position Acquisition, single plane MV")

Applicability Scope = RT Radiation "AP"

## Subtask 1

Index = 1

Workitem Code = (121702, DCM, "RT Patient Position Acquisition, single plane MV")

Acquisition Initiation = (S213504, 99SUP213 "Acquisition Initiation at specified value")  
(Start Parameter) = (S213520, DCM, "Meterset") = 10 MU

MV Generation = 6 MV

Projection Geometry = Gantry Angle 0

Position Reference Instance = RT Image "AP"

# Two Subtask Example kV/kV

<b>Task</b>	Workitem Code = (121705, DCM, "RT Patient Position Acquisition, dual plane kV") Applicability Scope = RT Radiation "AP"	
	<b>Subtask 1</b>	Index = 1 Workitem Code = (121704, DCM, "RT Patient Position Acquisition, single plane kV")  Acquisition Initiation = (S213502, 99SUP213 "Acquisition Initiation before start of Radiation")  kV Generation = 80 kV Projection Geometry = Source Angle 0  Position Reference Instance = RT Image "AP"
	<b>Subtask 2</b>	Index = 2 Workitem Code = (121704, DCM, "RT Patient Position Acquisition, single plane kV")  Acquisition Initiation = (S213502, 99SUP213 "Acquisition Initiation before start of Radiation")  kV Generation = 80 kV Projection Geometry = Source Angle 90  Position Reference Instance = RT Image "LATR"

# Two Subtask Example kV/MV

<b>Task</b>	Workitem Code = (121706, DCM, "RT Patient Position Acquisition, dual plane kV/MV") Applicability Scope = RT Radiation "AP"	
	<b>Subtask 1</b>	Index = 1 Workitem Code = (121704, DCM, "RT Patient Position Acquisition, single plane kV")  Acquisition Initiation = (S213502, 99SUP213 "Acquisition Initiation before start of Radiation")  kV Generation = 80 kV Projection Geometry = Source Angle 90  Position Reference Instance = RT Image "LATR"
	<b>Subtask 2</b>	Index = 2 Workitem Code = (121702, DCM, "RT Patient Position Acquisition, single plane MV")  Acquisition Initiation = (S213502, 99SUP213 "Acquisition Initiation before start of Radiation")  MV Generation = 6 MV Projection Geometry = Source Angle 0  Position Reference Instance = RT Image "AP"

## **One or more Acquisition Tasks**

For example:

- Task 1: One KV/MV Image pair prior to therapeutic beam
- Task 2: 5 MV Images during beam
- Task 3: One KV Image after beam

A task applies to:

- a set of RT Radiation Sets
- or a set RT Radiations
- or a Treatment Position group.

## **One or more Subtasks per Task.**

Per example of above:

- Task 1: 2 subtasks: one for KV, one for MV
- Task 2: 1 subtask for MV, with 5 trigger values defined
- Task 3: 1 subtask for MV



# Acq Instr.: Specification Approaches

## **Parameters are specified by:**

### **Indirectly by Protocol**

- Refer to a protocols knows to the acquisition device
  - by Code, or
  - by ID
- User may fine-tune this protocol at the acquisition device any time
  - Protocol identification stays the same
  - Protocol Version tracking out of scope
  - Device – based settings may be traced locally at the device

### **Directly by explicit Parameters:**

- As indicated in the following slides

## **Any combination of Protocol-inferred and explicit Parameters supported**

Addresses variability of devices in terms of

- Technology
- Generation

## **Basis: Equipment FOR**

- Same approach as used for RT Radiation IODs as well

## **Device Geometries**

Transformation Matrix from Equipment FOR to

- Imaging Source Coordinate System
- Image Receptor Coordinate System

User-readable decomposition optionally supported for applications, which can't do this

- concept as used in RT Radiations as well

## **Patient Positioner Geometry**

Use of existing 2<sup>nd</sup> Generation Approach

- Relate Patient FOR to Equipment FOR
- Library Approach
  - Specify Patient Position once
  - Apply many times by reference, since most treatments have static positions, but some do not

## **Generation of MV (therapeutic) Beam for Imaging**

- Use of 2<sup>nd</sup> Gen Radiation Generation Macro
- Covers MV Photons and Particles
- Incl. all beam generation specifics for the therapeutic beam devices

## **Generation of KV (therapeutic) Beam for Imaging**

- Use of existing (KV) X-Ray Attributes
- Covers KV Photons

(future outlook: Addition of other technologies as needed)

# Main Editor



**Ulrich Busch**

**Member WG-07**

**Individual**

**[ulrich.busch@bluewin.ch](mailto:ulrich.busch@bluewin.ch)**